# **Temposonics**®

Absolute, Non-Contact Position Sensors

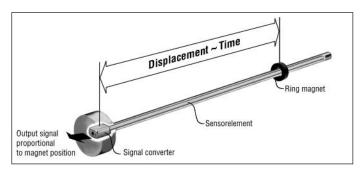


## **G-Series** SSI

**Temposonics®-GB**Measuring length 50 - 3250 mm



- Perfect data transmission 5 µm
- Absolute Sensor for Hydraulic Cylinders, without re-homing
- Stainless Steel Rod Sensor
- Contactless Sensing with Highest Durability
- Rugged Industrial Sensor, EMC shielded and CE certified
- ullet Superior Acuracy: Linearity Tolerance better 0,02 %
- Repeatability 0,001 %
- Resolution up to 5 µm
- Direct 25/24 bit SSI output (Gray or Binary)



#### Magnetostriction

The absolute **Temposonics**® linear position sensors are based on the MTS developed magnetostrictive measurement principle. That combines various magneto-mechanical effects and uses the physical height precise speed-measurement of an ultrasonic wave (torsion pulse in its sensor element) for position detecting. Sensor integrated signal processing transforms the measurements directly into market standard outputs. The contactless principle - an external movable magnet marks the position - eliminates the wear, noise and erroneous signal problems and guarantees the best durability without any recalibration.

### Form factor

These compact stainless steel position sensors are designed for instalation into standard hydrocylinders, specifically for use with clevis head or any space limited cylinder applications.

#### Simple mechanics

- The sensor head accommodates the electronics with active signal conditioning
- The pressure-proof sensor pipe with fitting flange protects the internal sensor element. It fits into the bored piston rod.
- The position magnet fixed at the piston bottom - drives wearfree over the sensor's stroke and starts the measurement signal through sensor rod wall.



SSI

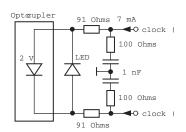
#### Temposonics®-GB Pressure Proof Sensor for Standard Hydrocylinders

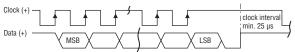
The interace of Temposonics®-GB **linear** sensors fulfil all requirements of the SSI standard for absolute rotary transducers.

Its displacement value is encoded in a 25- or 24-bit Binary or Gray code format and transmitted at very high speed via a serial type interface in RS 422 standard to the control device. SSI provides effectivesynchronization in a closed-loop control system. A clock pulse train from a controller is used to gate out sensor data.

#### Measuring range

The output of position values are coresponding with the selected resolution scale. The start position of electrical stroke is here factory set at 40 mm.





#### Measuring frequency

Measuring range:	300	750	1000	2000	3250 mm
Measurments/second:	3,7	3,0	2,3	1,2	0,8 kHz

Data transfer speed: 70 kBaud ... 1,5 MBaud

Depending on controller selected baud rate, following maximum cable length

is permitted.

 Cable length:
 < 3</th>
 < 50</th>
 < 100</th>
 < 200</th>
 < 400 m</th>

 Baud rate:
 1,5 MBd
 < 400 kBd</td>
 < 300 kBd</td>
 < 200 kBd</td>
 < 100kBd</td>

#### Example:

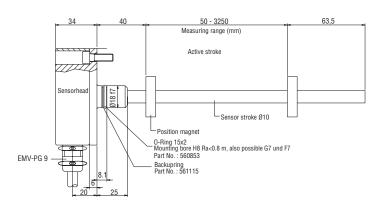
Resolution: 0,01 mm Mounting zone: 40 mm Measuring length: 300 mm Measuring direction: forward

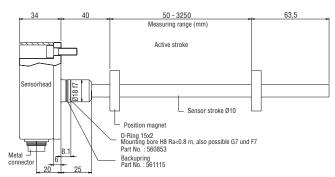
Measuring range	Position value
Start position = mm	4000 = 40 mm
Middle = 150 mm	19000 = 190 mm
End position = 300 mm	34000 = 340 mm
Start position, underflow	< 4000 = < 40 mm
End position, small overflow	> 34000 = > 340 mm
End position exceeded or	
position magnet error	Alarm value = 000000

#### **Technical Data**

Input			
Measuring Variable	Displacement		
Measuring Range	50 - 3250 mm		
Output			
Interface	SSI (Synchronous Serial Interface), RS 422 standard		
Data format	Binary or Gray encodes		
Data length	25 or 24 bit (upon request)		
Accuracy			
Resolution	5/10/20/50/100 μm		
Linearity	$< \pm 0.02 \%$ F.S. (Minimum $\pm 60 \mu m$ )		
Repeatability	< ± 0,001 % F.S.		
Temperature coefficient	< 15 ppm/°C		
Operating conditions			
Magnet speed	any		
Operating temperature	-40° C +75° C		
Pressure rating	350 bar, 700 bar peak		
Enclosure	IP 67 if cable connector is correctly fitted		
Shock rating	100 g (Single hit) / IEC-Standard 68-2-27		
Vibration rating	5g / 10-150 Hz, IEC-Standard68-2-6		
EMC Test	Electromagnetic emmision EN 61000-6-3		
	Electromagnetic immunity EN 61000-6-2 (EN 61326/A1)		
	EN 61000-4, Criteria A, CE qualified		
	EN 61000-4-2/3/4/6, Criterium A CE qualified		
Form factor / Material			
Sensor head	Stainless steel 1.4305 / AISI 303		
Rod with flange	Stainless steel 1.4301 / AISI 304		
Magnet Type	Ring magnet, PA-Ferrit		
Installation			
Mounting	Any orientation		
Sensor mounting	Flange Ø18h 6, 6 screws (ISO 4762)		
Electrical Connection			
Connection Type	7 pin connector M16 x 0,75 or cable outlet (PUR cable 3x2x0,25 mm², Ø 7,9 mm)		
Input voltage	24 VDC (+20 % / -15 %)		
- Polarity protection	Up to 30 VDC		
- Overvoltage protection	Up to 36 VDC		
Current consumption	50 - mA, stroke length dependent		
Ripple	< 1 % peak to peak 500VDC (DC ground to machine ground)		

MTS Sensors I 2 I





#### 2. 130 0. 123

#### 64.120 64.43 64.44 64.45 6

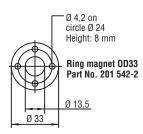
#### Any fitting position Simple mounting Small installation dimensions

The sensor's high-pressure, stainless steel tube with fitting flange will be fixed via 6 machine screws  $M6 \times 16 \times A2-70$  (ISO 4762) through the bores in the sensor head. The hydraulic sealing requires the use of a supplied O-Ring 15 x 2. Using ferromagnetic supports, note that the magnet must be mounted with non-ferrous spacer and screws.

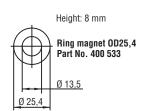
#### Position magnet

For accurate position measurements mount the magnet with non-ferrous fastening material (screws, supports ect.). Using ferromagnetic supports, note that the magnet must be mounted with non-ferrous spacer of 5 mm minimum and screws. Note the minimum mounting dimensions as illustrated right.

#### **Position magnets**



Composite PA-Ferrite-GF20 Weigth ca. 14 g Operating temperature: -40 ... +100°C Surface pressure max. 40 N/mm² Fastening Torque for M4 screws max. 1 Nm



Composite: PA-Ferrite Weigth ca. 10g Operating temperature: -40 ... +100°C Surface pressure max. 40 N/mm²

#### **Cylinder installation**

Use a rod bush (e. g. teflon) to prevent wear on the magnet and the sensor pipe.

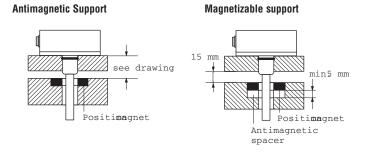
The bore in the piston rod is dependent on hydraulic pressure and piston velocity ect.

The minimum drilling must be 13 mm. Do not exceed the 700 bar peak pressure.

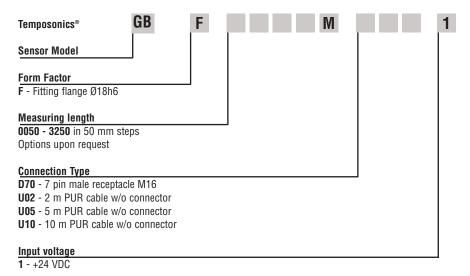
Wiring	Pin	Cable	Function
	1	Gray	Data (-)
1	2	Pink	Data (+)
(6 7)	3	Yellow	Clock (+)
(0 3)	4	Green	Clock (-)
(4 <sub>0</sub> 5/	5	Brown	+24 VDC
	6	White	0 V (GND)
	7	do not connect	

#### Note:

Application tht can damage the integral cable, please take connector output version. Sensor electronics and integral cable are encapsolated completely. Reparing electronic module is impossible.







 Stroke length Standard

 Stroke
 Ordering steps

 < 500 mm</td>
 5 mm

 500 - 750
 10 mm

 750 - 1000
 25 mm

 1000 - 2500
 50 mm

 > 2500
 100 mm

## Signal Output

\$ (1)(2)(3)(4)(5)(6) SSI (Synchronous Serial Interface)

(1) Data length: 1 - 25 bit • 2 - 24 bit (2) Output format: B - Binary • G - Gray

(3) Resolution (mm): 1 - 0,005 • 2 - 0,01 • 3 - 0,05 • 4 - 0,1 • 5 - 0,02

(4) Performance 1 - Standard

(5)(6) Options: 00 - Forward measurement • 01 - Reverse measurement

02 - Forward, synchronous measurement

#### On Delivery

Sensor with O-Ring,

Magnet (below) must be ordered separately

### Accessories (selected)

Description	Part No.
Position magnet OD33	201 542-2
Position magnet OD25,4	400 533
7 pin female cable connector M16	370 624
7 pin 90° female cable connector M16	560 779
PUR cable 3x2x0,25 mm <sup>2</sup>	530115
O-Ring 15 x 2 Fluorelastomer FPM 75	560 853
Backup ring	561 115
MTS-Service tools:	
PC-Programmer R-SSI incl. power supply	253 135
(100-240 VAC/24 VDC), connection cable	
and programming software (CD)	
SSI display and control unit (96x48x150 mm)	IX 340

#### Cable connector

(recommended, not on delivery)



7 pin female cable connector M16 Part No. 370 624



7 pin  $90^{\circ}$  female cable connector M16 **Part No. 560 779** 

Housing: Zinc, nickle plated Termination: Solder Contact Insert: Silver plated Cable clamp: PG9

Cable-Ø: 8 mm

#### Document Part Number: 25052012 (EN)

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